

# 9. Optimization

Marcus Denker

# Roadmap

- > Introduction
- > Optimizations in the Back-end
- > The Optimizer
- > SSA Optimizations
- > Advanced Optimizations



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# Optimization: The Idea

- > Transform the program to improve efficiency
- > **Performance:** faster execution
- > **Size:** smaller executable, smaller memory footprint

Tradeoffs:

1) **Performance vs. Size**

2) **Compilation speed and memory**

# No Magic Bullet!

- > There is no perfect optimizer
- > Example: optimize for simplicity

Opt(P): Smallest Program

Q: Program with no output, does not stop

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```
L1 goto L1
```

# No Magic Bullet!

- > There is no perfect optimizer
- > Example: optimize for simplicity

Opt(P): Smallest Program  
Q: Program with no output, does not stop

Opt(Q)?

```
L1 goto L1
```

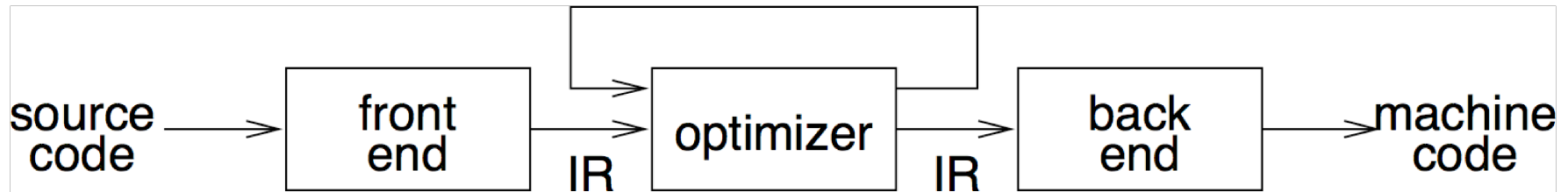
**Halting problem!**

## Another way to look at it...

- > Rice (1953): For every compiler there is a modified compiler that generates shorter code.
  
- > Proof: Assume there is a compiler  $U$  that generates the shortest optimized program  $\text{Opt}(P)$  for all  $P$ .
  - Assume  $P$  to be a program that does not stop and has no output
  - $\text{Opt}(P)$  will be `L1 goto L1`
  - Halting problem. Thus:  $U$  does not exist.
  
- > There will be always a better optimizer!
  - Job guarantee for compiler architects :-)



# Optimization on many levels



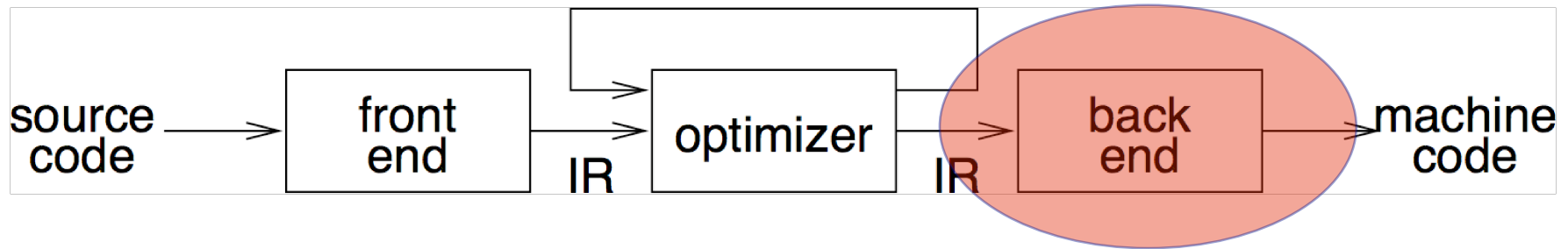
- > Optimizations both in the optimizer and back-end

# Roadmap

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# Optimizations in the Backend



- > Register Allocation
- > Instruction Selection
- > Peep-hole Optimization

# Register Allocation

- > Processor has only finite amount of registers
  - Can be very small (x86)
  
- > Temporary variables
  - non-overlapping temporaries can share one register
  
- > Passing arguments via registers
  
  
- > Optimizing register allocation very important for good performance
  - Especially on x86

# Instruction Selection

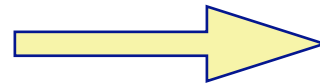
- > For every expression, there are many ways to realize them for a processor
- > Example: Multiplication\*2 can be done by bit-shift

*Instruction selection is a form of optimization*

# Peephole Optimization

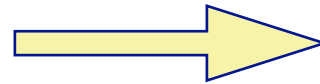
- > Simple local optimization
- > Look at code “through a hole”
  - replace sequences by known shorter ones
  - table pre-computed

```
store R,a;  
load a,R
```



```
store R,a;
```

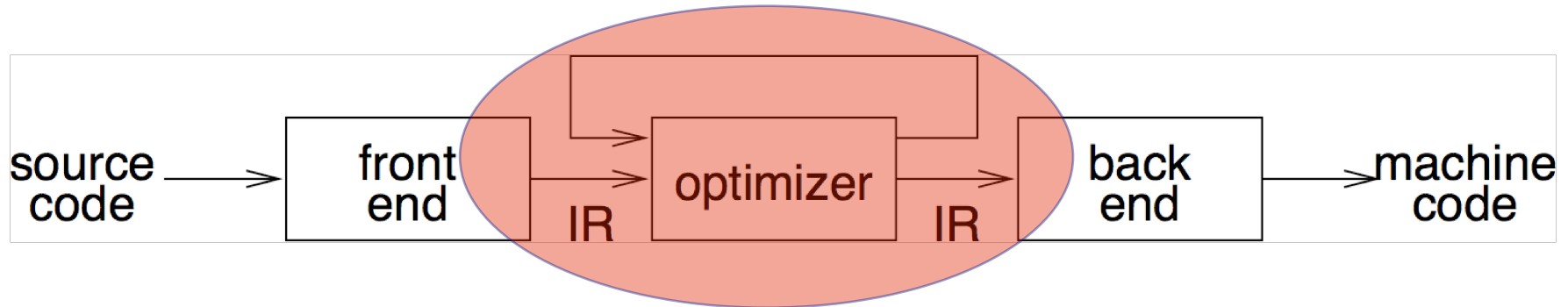
```
imul 2,R;
```



```
ashl 2,R;
```

*Important when using simple instruction selection!*

# Optimization on many levels



*Major work of optimization done in a special phase*

*Focus of this lecture*

# Different levels of IR

- > Different levels of IR for different optimizations
  
- > Example:
  - Array access as direct memory manipulation
  - We generate many simple to optimize integer expressions
  
- > We focus on high-level optimizations



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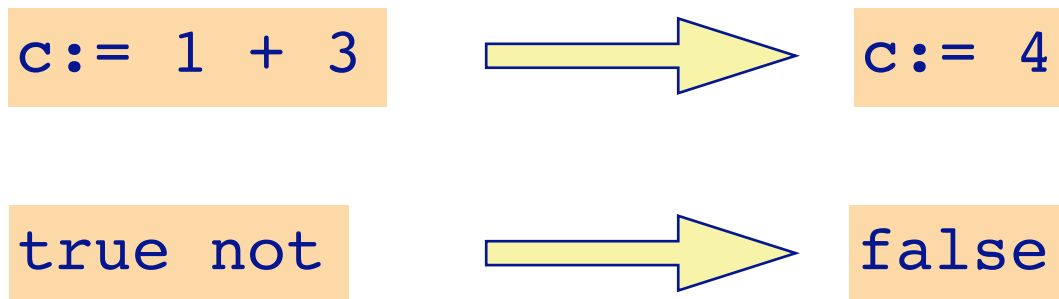


# Examples for Optimizations

- > Constant Folding / Propagation
- > Copy Propagation
- > Algebraic Simplifications
- > Strength Reduction
- > Dead Code Elimination
  - Structure Simplifications
- > Loop Optimizations
- > Partial Redundancy Elimination
- > Code Inlining

# Constant Folding

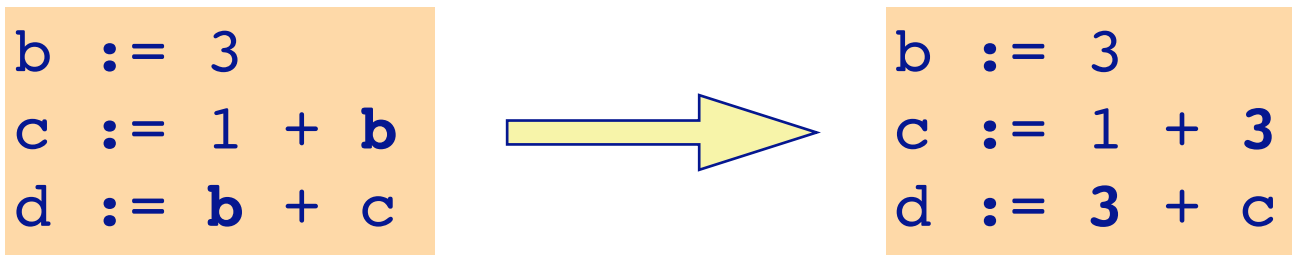
- > Evaluate constant expressions at compile time
- > Only possible when side-effect freeness guaranteed



Caveat: Floats — implementation could be different between machines!

# Constant Propagation

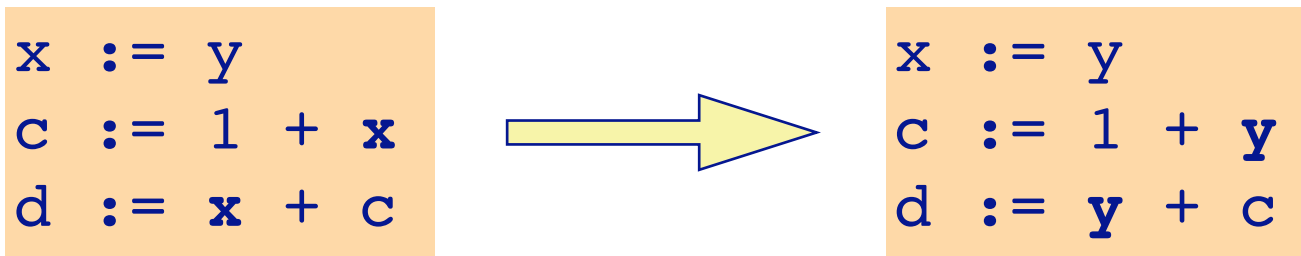
- > Variables that have constant value, e.g.  $c := 3$ 
  - Later uses of  $c$  can be replaced by the constant
  - If no change of  $c$  between!



Analysis needed, as  $b$  can be assigned more than once!

# Copy Propagation

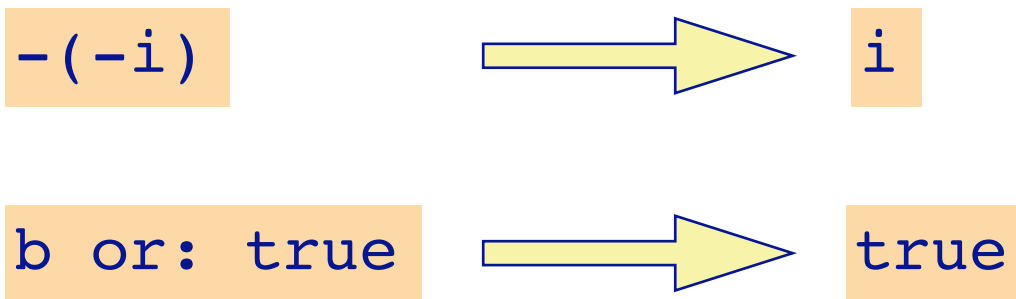
- > for a statement  $x := y$
- > replace later uses of  $x$  with  $y$ , if  $x$  and  $y$  have not been changed.



Analysis needed, as  $y$  and  $x$  can be assigned more than once!

# Algebraic Simplifications

- > Use algebraic properties to simplify expressions

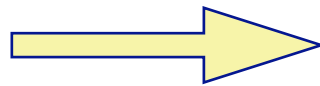


*Important to simplify code for later optimizations*

# Strength Reduction

- > Replace expensive operations with simpler ones
- > Example: Multiplications replaced by additions

```
y := x * 2
```



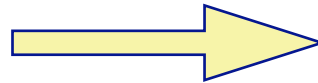
```
y := x + x
```

*Peephole optimizations are often strength reductions*

# Dead Code

- > Remove unnecessary code
  - e.g. variables assigned but never read

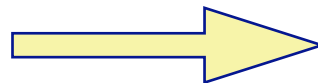
```
b := 3
c := 1 + 3
d := 3 + c
```



```
c := 1 + 3
d := 3 + c
```

- > Remove code never reached

```
if (false)
{a := 5}
```



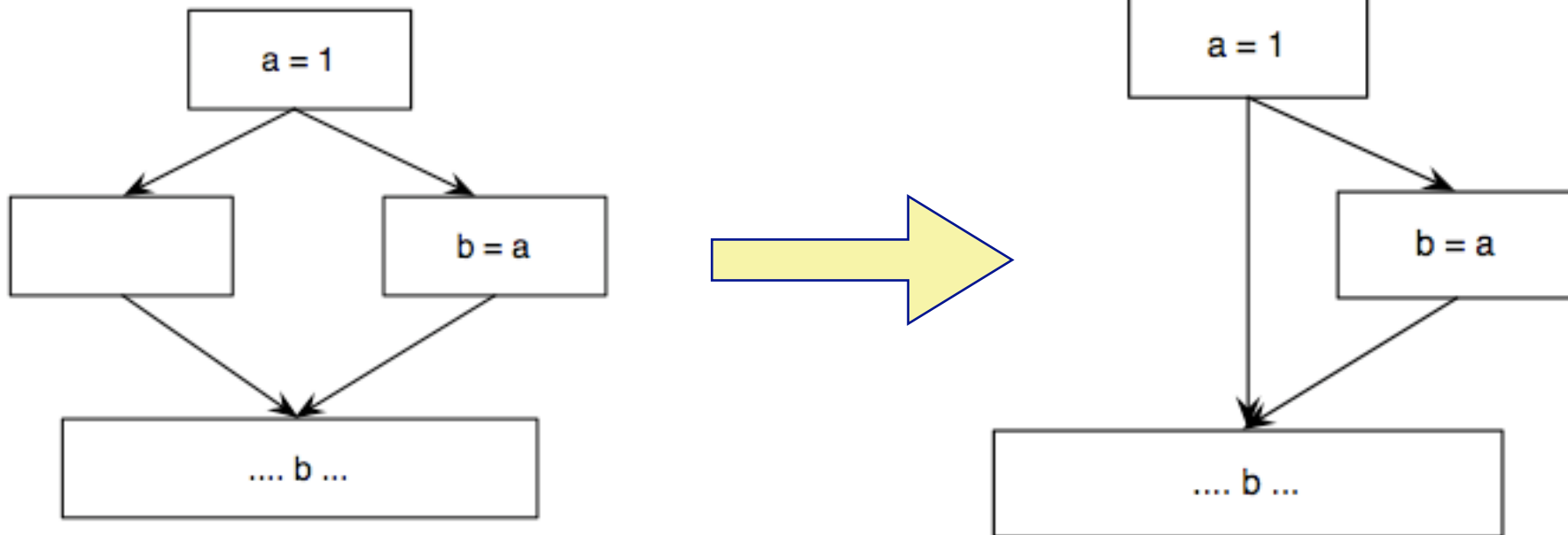
```
if (false)
{}
```



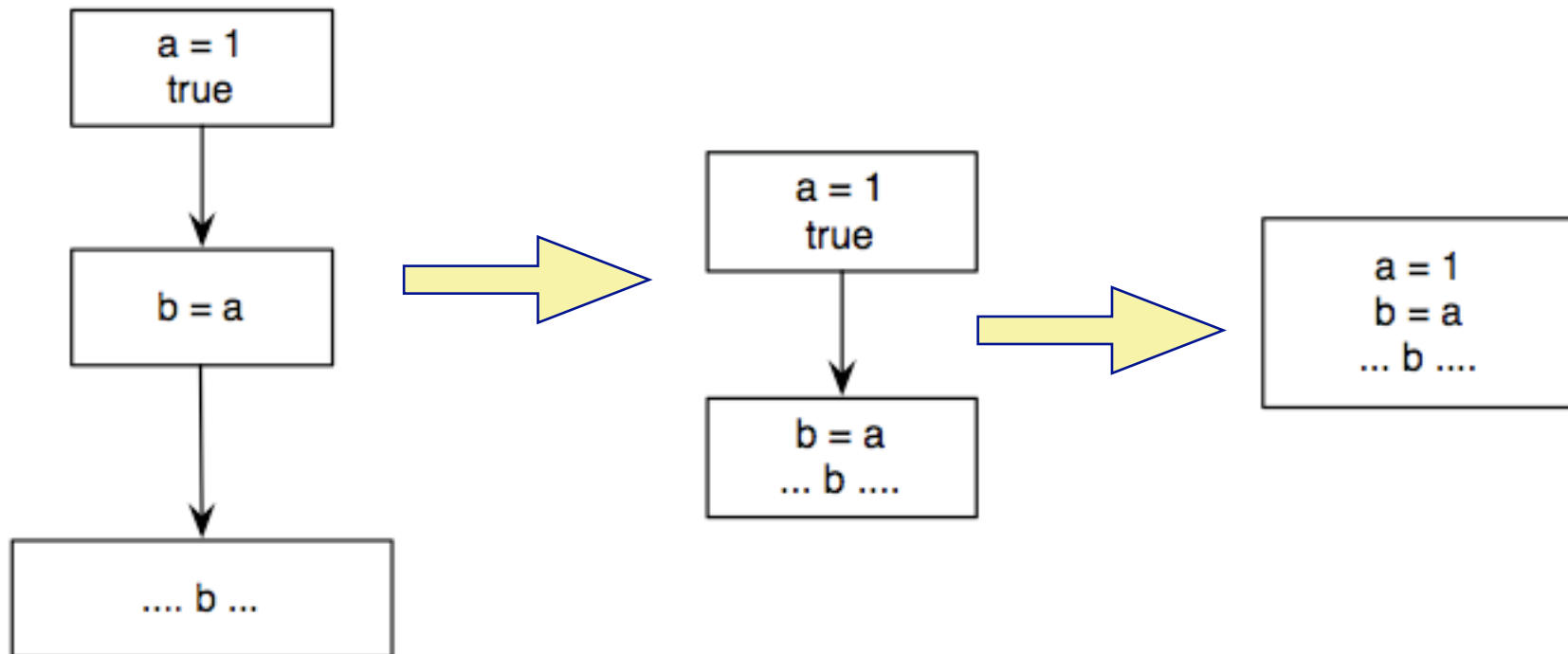
# Simplify Structure

- > Similar to dead code: Simplify CFG Structure
- > Optimizations will degenerate CFG
- > Needs to be cleaned to simplify further optimization!

# Delete Empty Basic Blocks



# Fuse Basic Blocks



# Common Subexpression Elimination (CSE)

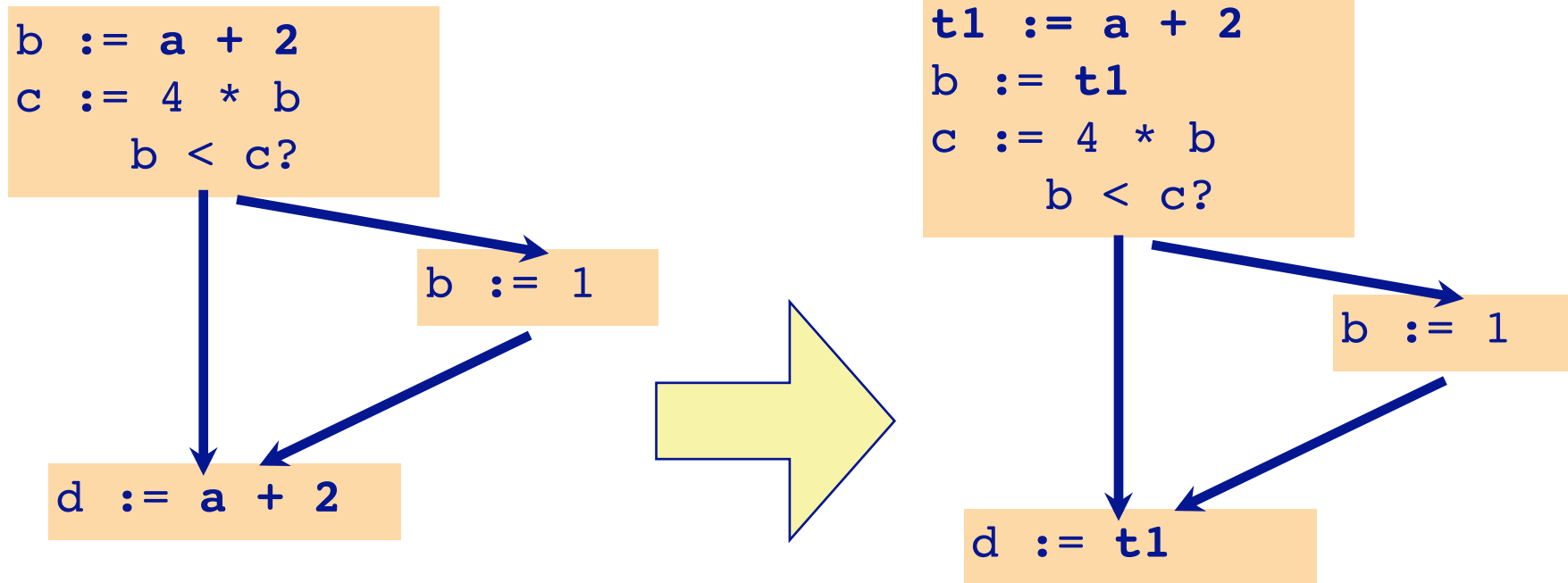
## Common Subexpression:

- There is another occurrence of the expression whose evaluation always precedes this one
- operands remain unchanged

**Local** (inside one basic block): When building IR

**Global** (complete flow-graph)

# Example CSE

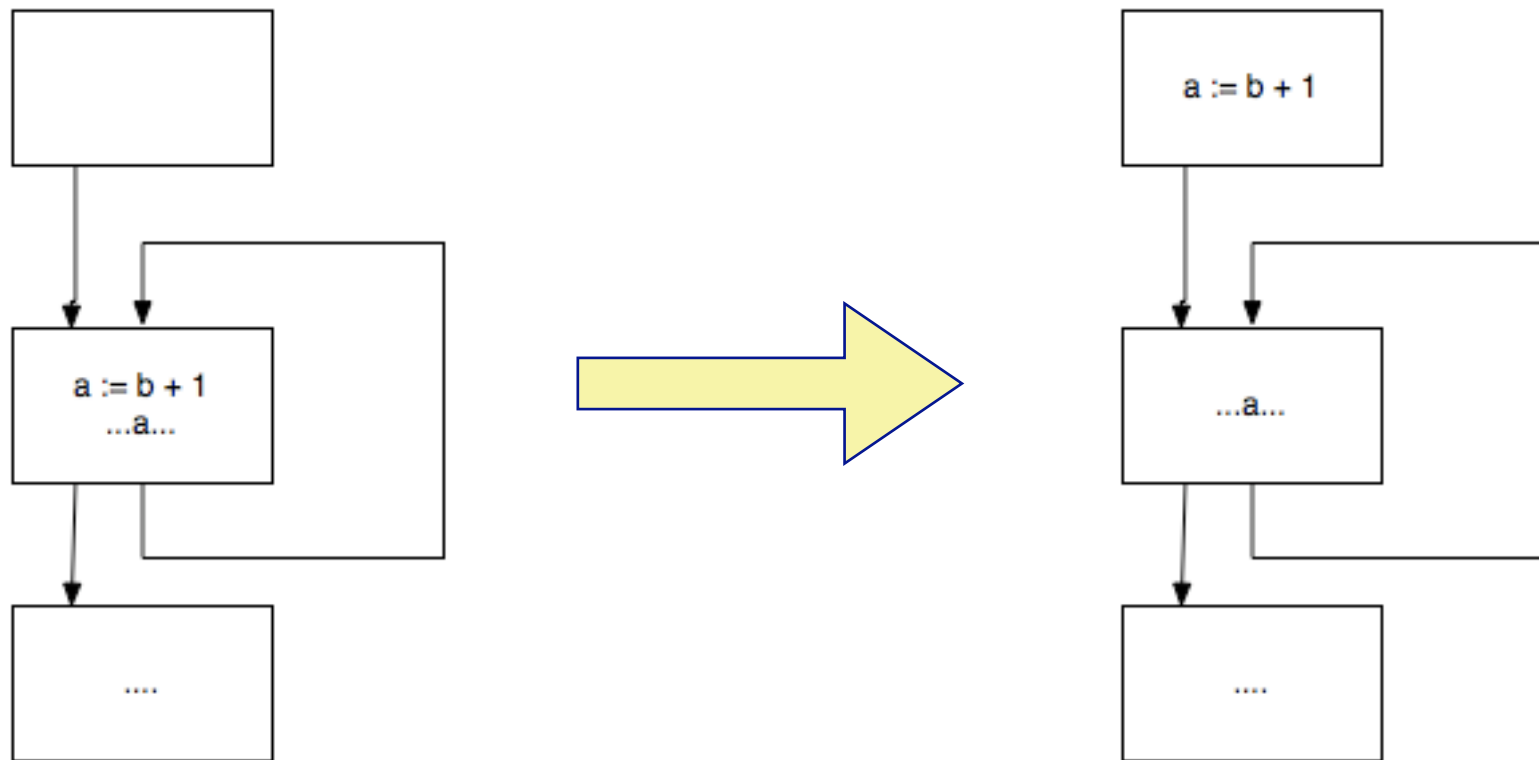


# Loop Optimizations

- > Optimizing code in loops is important
  - often executed, large payoff
- > All optimizations help when applied to loop-bodies
- > Some optimizations are loop specific

# Loop Invariant Code Motion

- > Move expressions that are constant over all iterations out of the loop

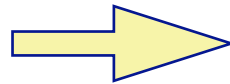


# Induction Variable Optimizations

- > Values of variables form an arithmetic progression

```
integer a(100)
do i = 1, 100
  a(i) = 202 - 2 * i
endo
```

value assigned to *a*  
decreases by 2



```
integer a(100)
t1 := 202
do i = 1, 100
  t1 := t1 - 2
  a(i) = t1
endo
```

uses *Strength Reduction*



# Partial Redundancy Elimination (PRE)

- > Combines multiple optimizations:
  - global common-subexpression elimination
  - loop-invariant code motion
- > **Partial Redundancy:** computation done more than once on some path in the flow-graph
- > PRE: insert and delete code to minimize redundancy.

# Code Inlining

- > All optimization up to know where local to one procedure
- > Problem: procedures or functions are very short
  - Especially in good OO code!
- > Solution: Copy code of small procedures into the caller
  - OO: Polymorphic calls. Which method is called?

# Example: Inlining

```
a := power2(b)
```

```
power2(x) {  
    return x*x  
}
```



```
a := b * b
```

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# Repeat: SSA

- > SSA: Static Single Assignment Form
- > **Definition:** Every variable is only assigned once

# Properties

- > Definitions of variables (assignments) have a list of all uses
- > Variable uses (reads) point to the one definition
- > CFG of Basic Blocks

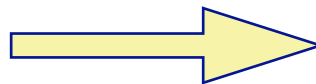
# Examples: Optimization on SSA

- > We take three simple ones:
  - Constant Propagation
  - Copy Propagation
  - Simple Dead Code Elimination

## Repeat: Constant Propagation

- > Variables that have constant value, e.g.  $c := 3$ 
  - Later uses of  $c$  can be replaced by the constant
  - If no change of  $c$  between!

```
b := 3
c := 1 + b
d := b + c
```



```
b := 3
c := 1 + 3
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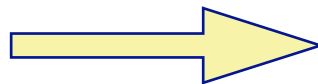
Analysis needed, as  $b$  can be assigned more than once!



# Constant Propagation and SSA

- > Variables are assigned once
- > We know that we can replace all uses by the constant!

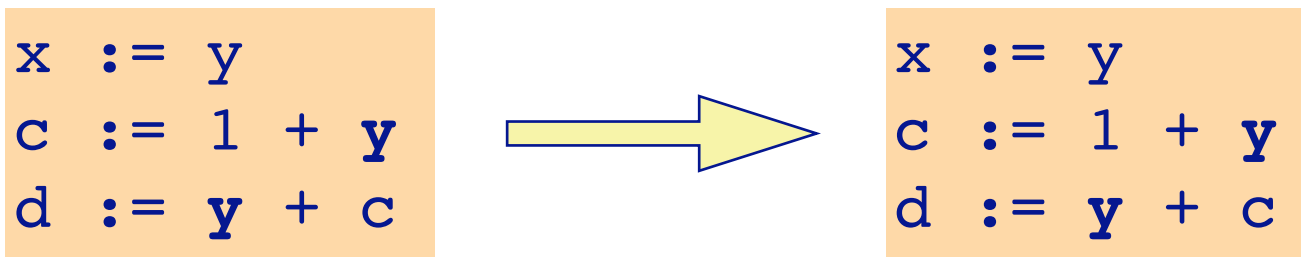
```
b1 := 3  
c1 := 1 + b1  
d1 := b1 + c1
```



```
b1 := 3  
c1 := 1 + 3  
d1 := 3 + c
```

## Repeat: Copy Propagation

- > for a statement  $x := y$
- > replace later uses of  $x$  with  $y$ , if  $x$  and  $y$  have not been changed.

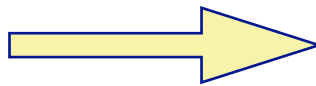


Analysis needed, as  $y$  and  $x$  can be assigned more than once!

# Copy Propagation And SSA

- > for a statement  $x1 := y1$
- > replace later uses of  $x1$  with  $y1$

```
x1 := y1  
c1 := 1 + x1  
d1 := x1 + c1
```



```
x1 := y1  
c1 := 1 + y1  
d1 := y1 + c1
```

# Dead Code Elimination and SSA

- > Variable is live if the list of uses is not empty.
- > Dead definitions can be deleted
  - (If there is no side-effect)

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# Advanced Optimizations

- > Optimizing for using multiple processors
  - Auto parallelization
  - Very active area of research (again)
  
- > Inter-procedural optimizations
  - Global view, not just one procedure
  
- > Profile-guided optimization
- > Vectorization
- > Dynamic optimization
  - Used in virtual machines (both hardware and language VM)

# Iterative Process

- > There is no general “right” order of optimizations
- > One optimization generates new opportunities for a preceding one.
- > Optimization is an iterative process

**Compile Time vs. Code Quality**

# What we have seen...

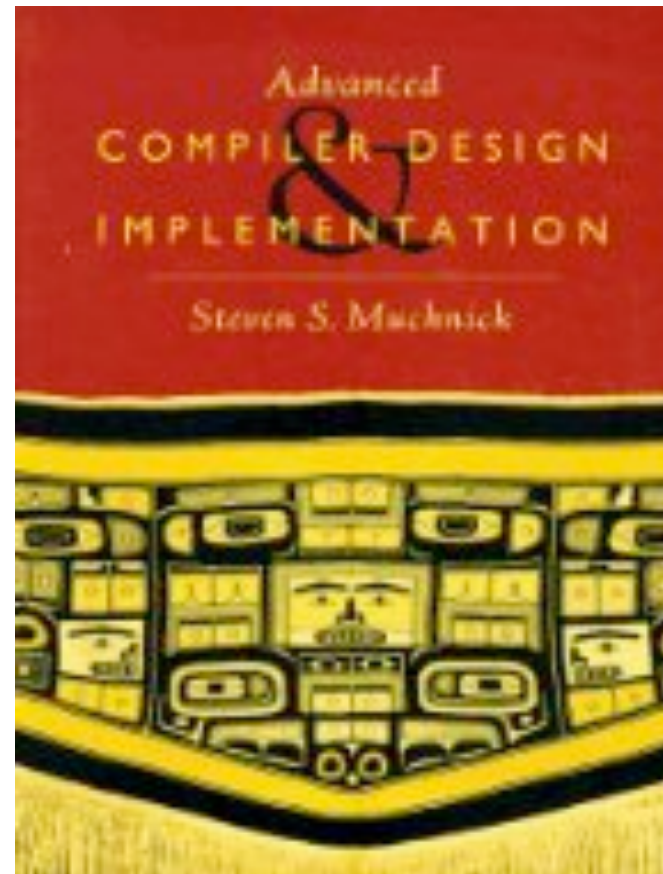
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# Literature






- > Muchnick: *Advanced Compiler Design and Implementation*
  - >600 pages on optimizations
- > Appel: *Modern Compiler Implementation in Java*
  - *The basics*



## ***What you should know!***


-  *Why do we optimize programs?*
-  *Is there an optimal optimizer?*
-  *Where in a compiler does optimization happen?*
-  *Can you explain constant propagation?*

## ***Can you answer these questions?***

-  *What makes SSA suitable for optimization?*
-  *When is a definition of a variable live in SSA Form?*
-  *Why don't we just optimize on the AST?*
-  *Why do we need to optimize IR on different levels?*
-  *In which order do we run the different optimizations?*

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